

Distributed by  
**Raymarine**

Any reference to Raytheon or RTN in this manual should be interpreted as Raymarine. The names Raytheon and RTN are owned by the Raytheon Company.

# ST3000 Wheel Pilot Quick Reference Guide

## Basic operation

**Auto mode**

**Entering Auto mode** (Engaging the autopilot)

**Making course changes**

**Returning to Standby** (Disengaging the autopilot)

**Returning to previous locked heading**

**Track mode**

**Entering Track mode** (from Auto or Wind Vane mode)

Press **-10** and **+10** to enter Track mode

then **-10** and **+10** to accept new heading

Press **STANDBY** or **AUTO** to exit.

**Wind Vane mode**

**Entering Wind Vane mode**

Press **STANDBY** or **AUTO** to exit Wind Vane mode.

**Using AutoTrack**

**Autopilot displays**

**Switching lighting on/off**  
(from Standby mode only)

Press **-1** and **+1** to switch between:

**L1** ON

**L0** OFF

Wait 10 sec to return to previous mode.

**Switching AutoSeastate on/off**  
(from Auto/Track/Wind Vane modes)

Press **-1** and **+1** to switch between:

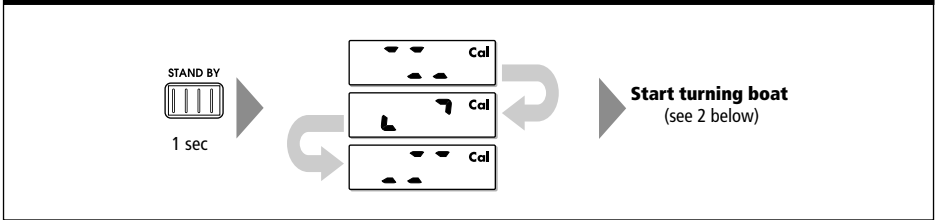
**A258°** ON

**A258°** OFF

# ST3000 Wheel Pilot Quick Reference Guide

## Compass calibration

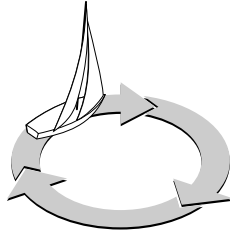
### 1 Enter compass calibration



### 2 Turn boat in slow circles

Turn the boat in slow circles so:

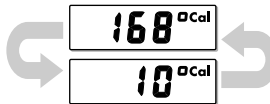
- boat's speed stays below 2 knots
- each circle takes at least 3 minutes



### 3 Autopilot displays amount of deviation detected

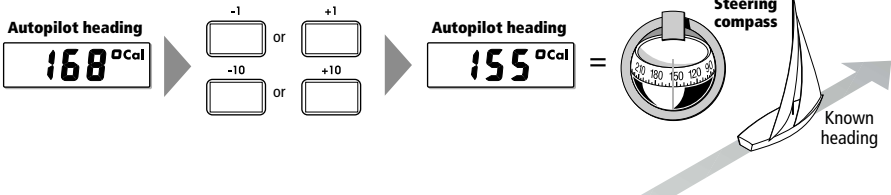
Keep turning the boat until the display alternates between:

- autopilot heading
- deviation detected

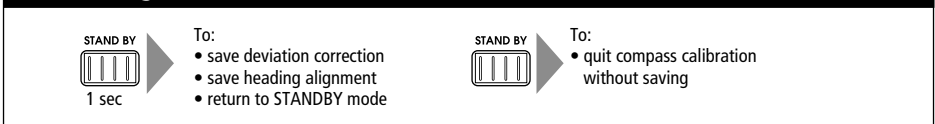


### 4 Align the autopilot heading

Adjust the autopilot heading to match the boat's steering compass



### 5 Save changes



D5660-1